

FIG. 1

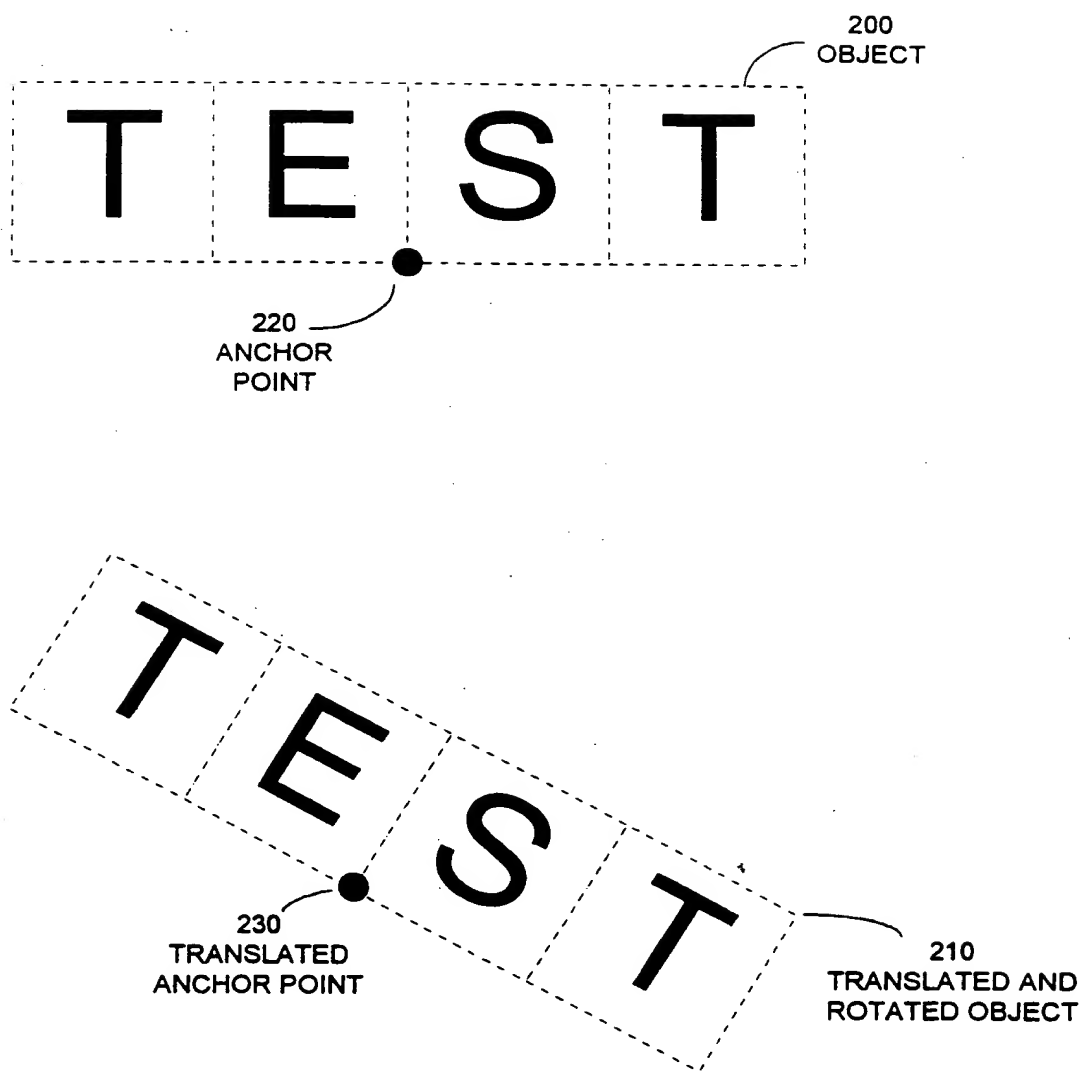


FIG. 2

$$M = M_ANCHOR * M_RESIZE * M_SKEW * M_ROTATE * M_TRANSLATE$$

$$M_ANCHOR = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ XANCHOR & YANCHOR & 1 \end{bmatrix}$$

$$M_RESIZE = \begin{bmatrix} XRESIZE & 0 & 0 \\ 0 & YRESIZE & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$M_SKEW = \begin{bmatrix} 1 & YSKEW & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$M_ROTATE = \begin{bmatrix} \cos(\text{BETA}) & \sin(\text{BETA}) & 0 \\ -\sin(\text{BETA}) & \cos(\text{BETA}) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$M_TRANSLATE = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ XPOSITION & YPOSITION & 1 \end{bmatrix}$$

FIG. 3

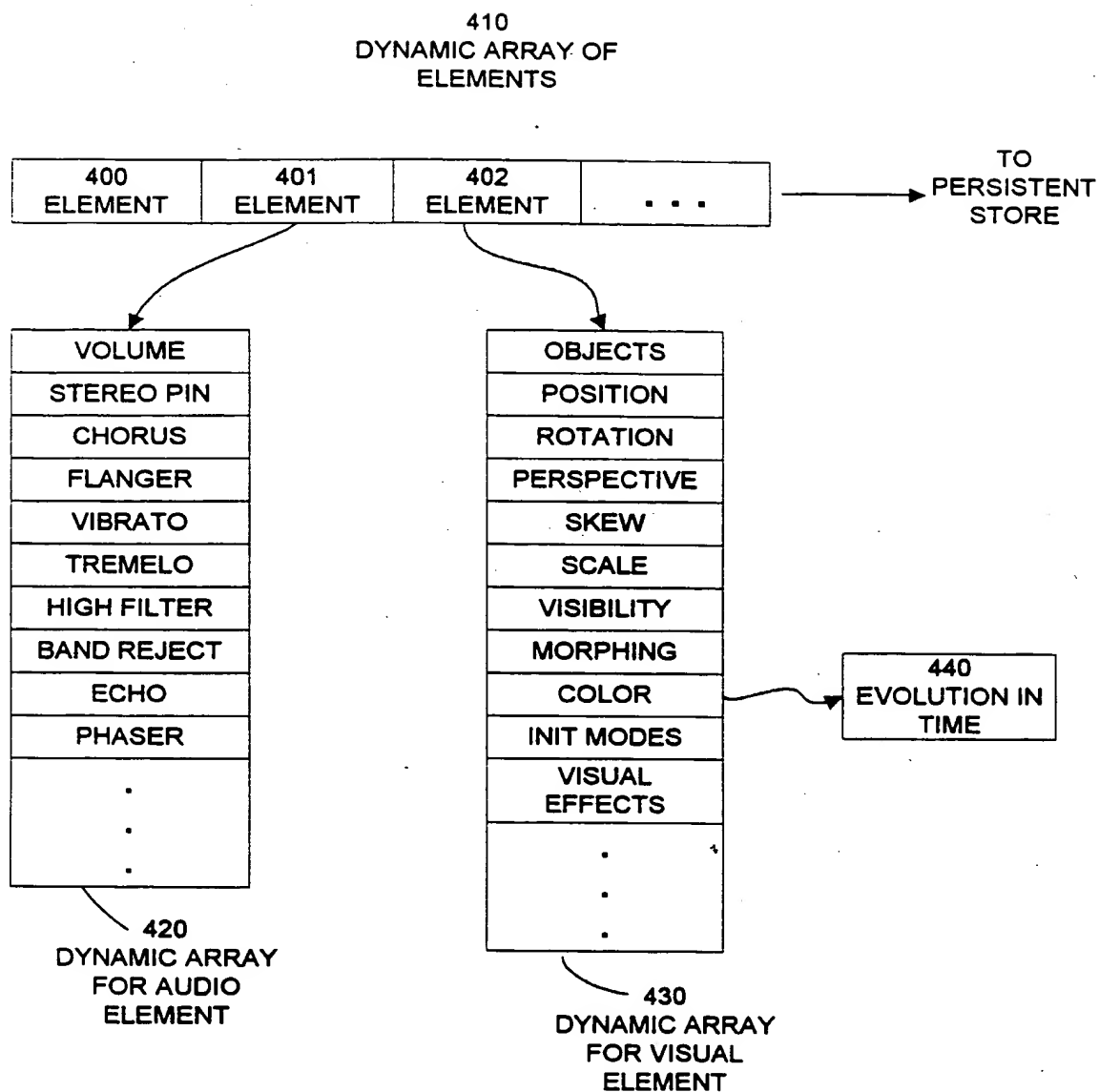


FIG. 4

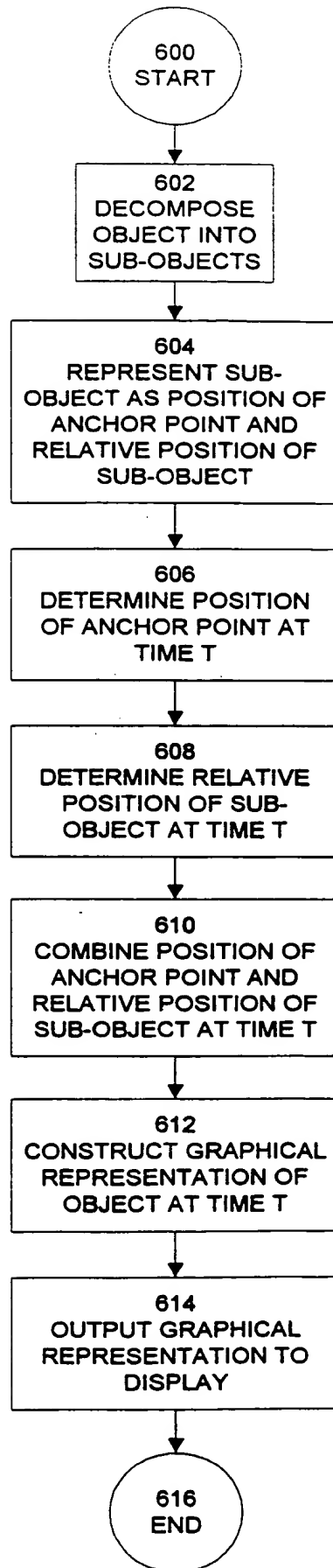


FIG. 6

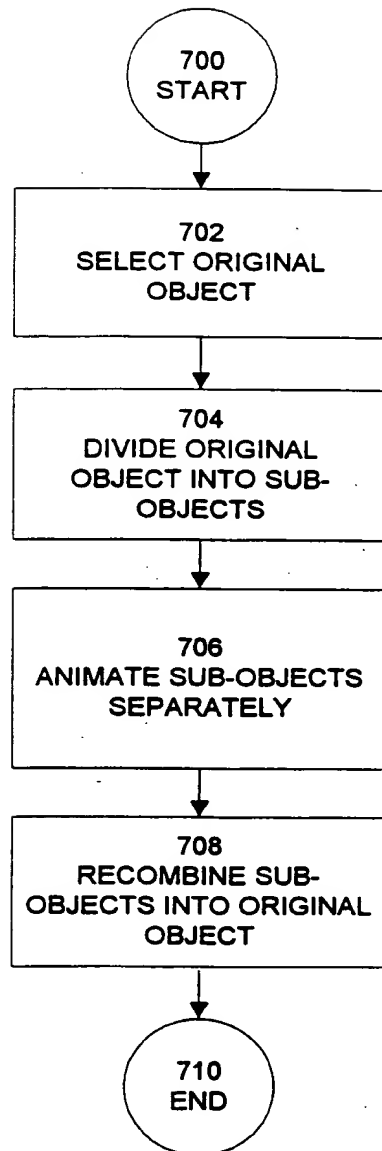


FIG. 7

FIG. 8 is a schematic diagram of a network system.

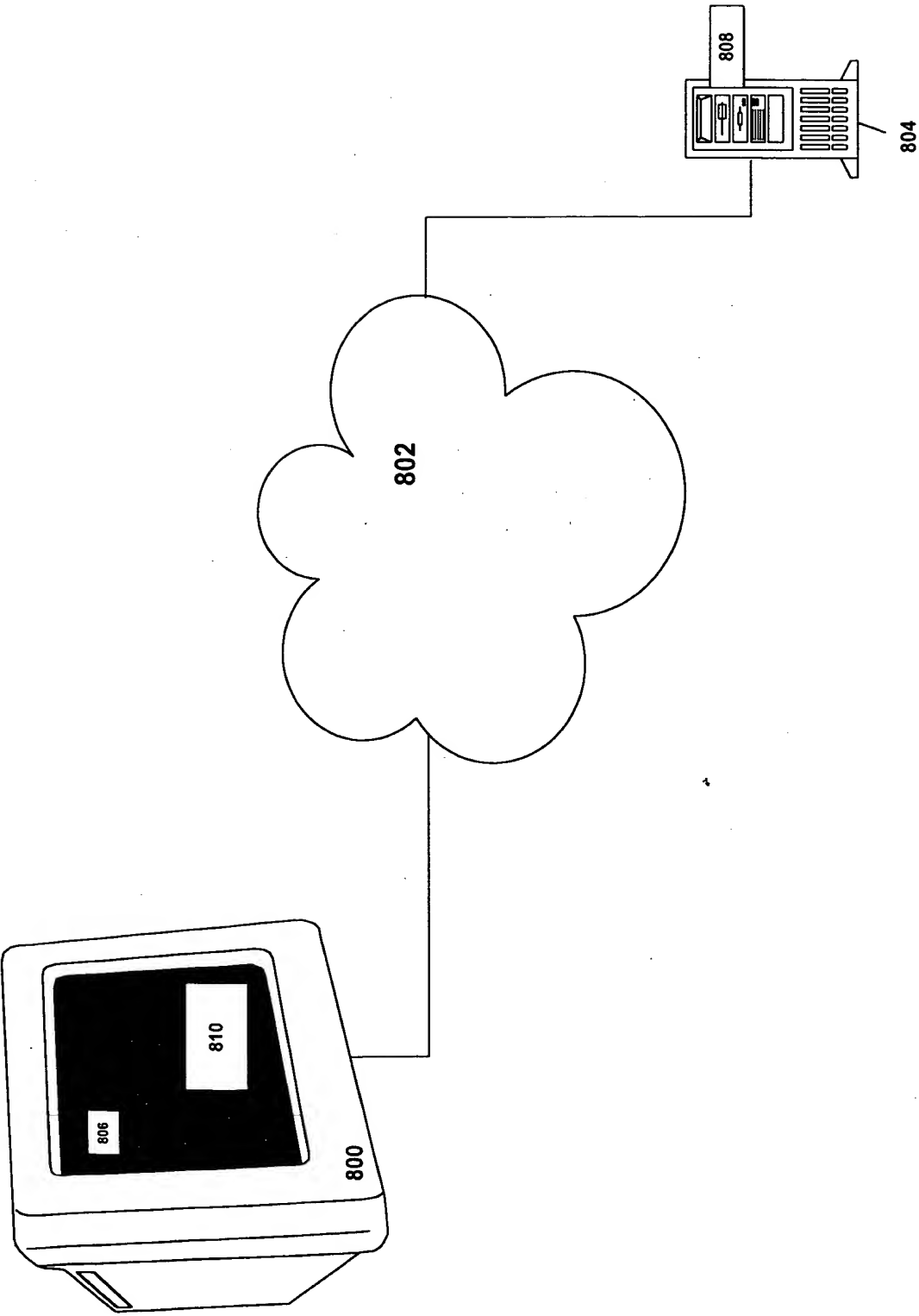


FIGURE 8

<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
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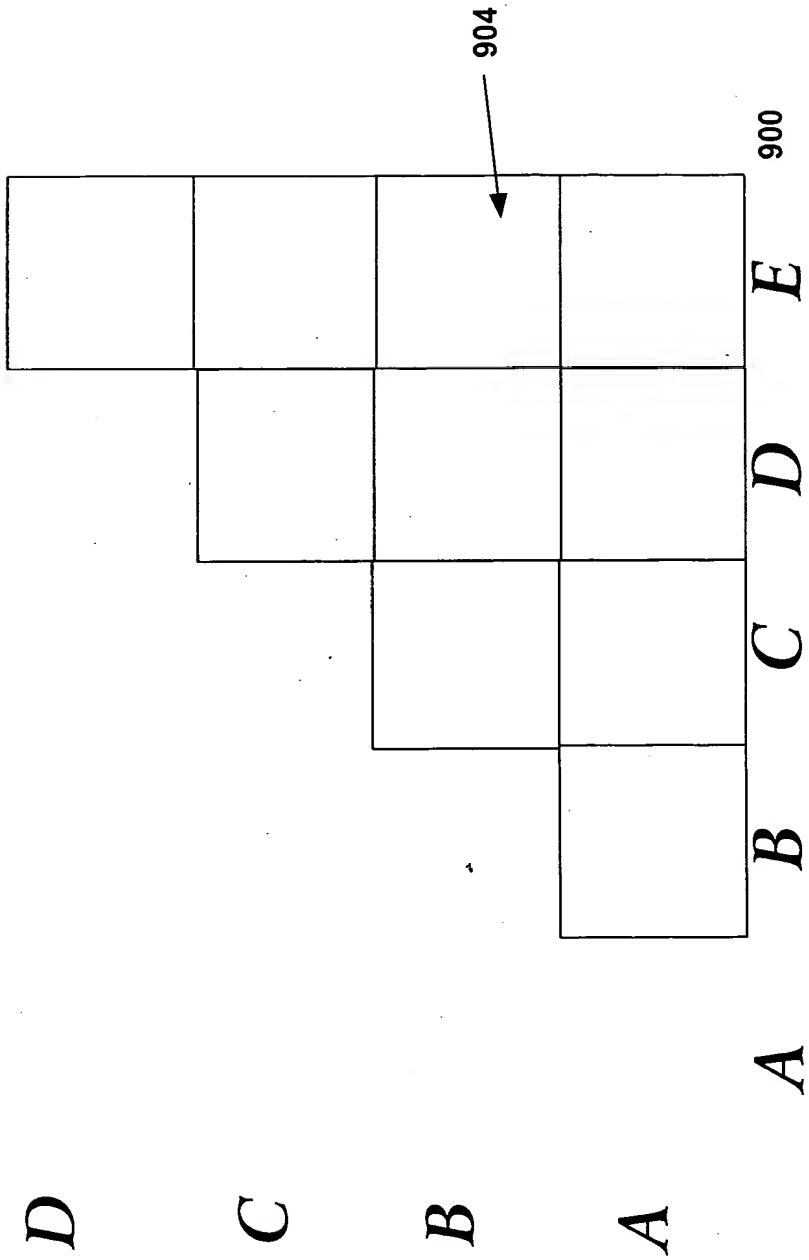


FIGURE 9